

MATH 242, LECTURE 15

0.1. Inverses of matrices.

Definition 1. The inverse of a square matrix M is one which we call M^{-1} (as opposed to $\frac{1}{M}$) where $MM^{-1} = I = M^{-1}M$.

Theorem 2. The inverse of the 2×2 matrix $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is $\begin{bmatrix} \frac{d}{ad-bc} & \frac{-b}{ad-bc} \\ \frac{-c}{ad-bc} & \frac{a}{ad-bc} \end{bmatrix}$.

Note that the number $ad - bc$ which appears everywhere in this formula has its own special name; it is the *determinant* of the matrix. If it is zero, then an inverse does not exist.

Example 3. Verify this theorem for the matrix $\begin{bmatrix} 5 & 7 \\ 2 & 3 \end{bmatrix}$.

There are formulae for inverting larger matrices, but they are complicated! Fortunately, we do not have to invert matrices by hand. Many graphing calculators, including the TI-83, have a function to invert a matrix. See the manual, linked to from the class page, to learn how.

0.2. Using inverses to solve linear systems. Let M be a square matrix, X be a column vector of variables and C be a column vector of constants (of compatible sizes). To solve the equation $MX = C$ we first find M^{-1} (if it exists) and then multiplying both sides by M^{-1} we get $M^{-1}MX = M^{-1}C$, or $IX = M^{-1}C$ or $X = M^{-1}C$.

So the steps to solve $MX = C$ are:

- (1) Find M^{-1} .
- (2) Compute the product $M^{-1}C$.
- (3) (For thoroughness) check that your answer works.

Example 4. Use matrix algebra to solve the system of equations $5x + 7y = 3$, $2x + 3y = -1$.

One great advantage to matrix methods is in solving related systems.

Example 5. Solve the matrix equation $\begin{bmatrix} 3 & 2 \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$. What if we replace $\begin{bmatrix} 5 \\ 6 \end{bmatrix}$ by $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$? By $\begin{bmatrix} -1 \\ \pi \end{bmatrix}$?

With these techniques (and calculators in hand) we can move on to swiftly solving problems with more variables.

Example 6. The average yield on A-bonds is 6%, on B-bonds is 7% and on C-bonds is 10%. Because of a hedging scheme, you must invest twice as much money in A bonds as C bonds. Find the amounts to invest for the following desired outcomes:

- \$25K invested with an annual return of \$1.8K.
- \$30K invested with an annual return of \$2.2K.
- \$40K invested with an annual return of \$2.9 K.

1. LINEAR INEQUALITIES

Having seen how matrices allow us to solve systems of linear equalities, we now move to *linear inequalities*.

Definition 7. A linear inequality in two variables is an equation of the form $ax + by \geq c$ (or $\leq c$ instead of $\geq c$), where a, b, c are numbers and x and y are variables or in many variables is one of the form

$$\begin{bmatrix} a & b & c & \cdots \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ \cdots \end{bmatrix} \geq p \text{ (or } \leq p \text{ instead of } \geq p) \text{ where } \begin{bmatrix} a & b & c & \cdots \end{bmatrix} \text{ is a row vector of numbers, } \begin{bmatrix} x \\ y \\ z \\ \cdots \end{bmatrix} \text{ is a column vector of variables, and } p \text{ is some number.}$$

Linear inequalities arise naturally as *constraints*. For example, $x \geq 0$ is a linear inequality which means that we only want to consider positive or zero values of x , a constraint we have seen for example when solving for lengths of objects (like fencing) or amount of some good to produce.

Because they are easier to visualize, we will focus on linear inequalities in two variables. The set of points which satisfies a linear inequality in two variables forms a *half-space*. We check this in examples before talking about the general case. Note that we will be using the funny convention (which will make sense later) of shading in the points which do *not* satisfy the inequality.

Example 8. Plot all points which (do not) satisfy $x \geq 0$; $y \leq 0$; $x - y < 0$; $x + y \geq 1$.

In general, the procedure to graph a the region satisfying a linear inequality is as follows:

- Graph the line defined by changing the inequality to an equality.
- Pick one point not on the line and test whether it satisfies the inequality.
- If the test point does satisfy the inequality, all of the other points on the same side of the line do, so shade all points on the other side of the line from the test point.
- If the test point does not satisfy the inequality, all other points on the same side of the line do not as well, so shade all points on the same side of the line as the test point.

This procedure works because, as we will see when we develop derivatives of functions of many variables, linear functions in any number of variables have constant derivatives, so once a linear function is greater than or less than a given value, it must continue to be so indefinitely. It is also helpful to think of the single variable case, and to look at the graph in the multi-variable case.

Example 9. Plot all points which satisfy $2x - 3y \leq 5$.

1.1. Multiple linear inequalities. Many familiar shapes can be described algebraically using multiple linear inequalities.

Example 10. The inequalities $x \geq 0$, $x \leq 5$, $y \geq -1$, $y \leq 3$ define a rectangle.

We formalize this as follows.

Definition 11. The solution set of a system of linear inequalities is the set of all points which satisfy all of the inequalities.

Example 12. Graph the solution set for the system of inequalities:

$$\begin{cases} x + y \geq 1 \\ x + y \leq 3 \\ 2x - y < 2 \end{cases}$$

Some basic terminology:

Definition 13. *The boundary lines for a system of inequalities are the lines defining by replacing inequalities by equalities. The boundary points are points on the boundary lines which lie next to the solution set. The corner points of a system are those boundary points which lie on more than one of the boundary lines.*

Example 14. *Graph the solution set, and identify the corner points for the systems:*

$$A : \begin{cases} x - y \geq -1 \\ x + y \leq 2 \\ y \geq -1 \end{cases} \quad B : \begin{cases} x - y \geq 2 \\ x + y \geq 5 \\ x, y \geq 0 \end{cases}$$

One last piece of terminology:

Definition 15. *A solution set is bounded if it is contained in some (larger) rectangle. If there is no such rectangle, then it is unbounded.*

Informally, an unbounded region has points which go to infinity in some direction. We finish by checking which regions we have seen are bounded and unbounded.